

Principle of Operation

SSR Switching Characteristics

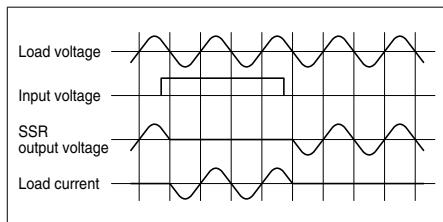
1. SSR for AC Loads

(1) Zero-crossing SSR

The zero-crossing SSR uses a phototriac coupler to isolate the input from the output (see the circuit configuration on the previous page). When the input signal is activated, the internal zero-crossing detector circuit triggers the triac to turn on as the AC load voltage crosses zero. The load current is maintained by the triac's latching effect after the input signal is deactivated, until the triac is turned off when the load voltage crosses zero. The following describes voltage and current wave forms for different types of loads:

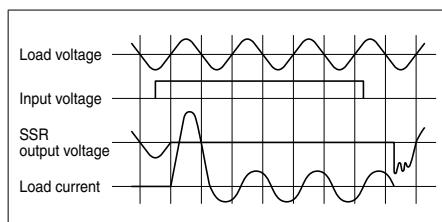
• Resistive loads

Since resistive loads cause no phase shift between the voltage and current, the triac turns on when the AC load voltage crosses zero after the input signal is activated. The SSR turns off when the AC load voltage crosses zero and the load current is turned off after the input signal is subsequently deactivated.

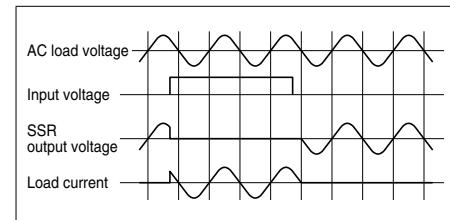


• Inductive loads

The SSR turns on when the load voltage crosses zero after the input signal is activated. It turns off when the load current subsequently crosses zero after the input signal is deactivated. A phase difference between the voltage and current may supply a transient spike to the SSR when it is turned off. While the snubber circuit absorbs this spike, an excessively large spike may result in a dv/dt error in the SSR's internal triac.



• Resistive loads



2. SSR for DC Loads

The SSR for DC loads uses a MOS-FET driver to isolate the input from the output. The output immediately responds to the input, since the MOS-FET driver directly turns the output MOS-FET ON or OFF.